

#### **Pricing in Telecommunication Networks: From Wireless to Optical Networks**

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# Motivation

- From centralized to distributed protocols
  - Network size growth
  - Resource allocation (power, bandwidth,etc.)
- Tools: Optimization vs. Game theory
  - Agents: different channels
  - Strategy: feasible power consumptions
  - Preference: utility function
  - Information: local and myopic
  - Non-cooperative
- Implementation
  - Pricing schemes (proportional pricing, decentralized pricing, auctions, etc.)
- Example: Wireless and Optical Networks





## Wireless Network

- CDMA uplink power control:
  - Conserve battery energy
  - Minimize the effect of interference  $\rightarrow$  SNR





# **Game Formulation**

- A game defined by  $\langle N, (A_i), (J_i) \rangle$ 
  - N=(1,2,...M), number of players
  - $(A_i)_{i \in N}$ : set of actions
  - $(J_i)_{i \in N}$ : preference relations represented by payoff functions:

$$J_i(p_i, p_{-i}) = \underbrace{\lambda_i p_i}_{\text{cost}} - \underbrace{\ln(1 + \gamma_i)}_{\text{utility}} \quad \forall i$$

(SNR) 
$$\gamma_i = L \frac{h_i p_i}{\sum_{i \neq j} h_i p_j + \sigma^2}$$

• Each user i has her own best response as function:

$$BR_i(p_i, p_{-i}) = rg\max_{p_i} J_i(p_i, p_{-i})$$

• Nash equilibrium is unique when only one  $p^*$  satisfies

$$BR_1(p^*) = BR_2(p^*) = \dots = BR_N(p^*)$$





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#### Nash Equilibrium





"Best result comes when one is doing what is best for himself and the group."



## **Nash Solution and Algorithms**

Unique solution of  $Ap^* = b \iff A$  is strictly diagonally dominant  $BR_1(p^*) = BR_2(p^*) = \dots = BR_N(p^*)$ 

# $$\begin{split} & \left\{ \begin{aligned} p_i^{(n+1)}(p_{-1}^{(n)},\lambda_i) = \frac{1}{\lambda_i} - \frac{1}{Lh_i} \left( \sum_{j\neq i} h_j p_j^{(n)} + \sigma^2 \right) & \text{if } \sum_{j\neq i} h_j p_j^{(n)} \leq \frac{Lh_i}{\lambda_i - \sigma^2} \\ p_i^{(n+1)}(p_{-1}^{(n)},\lambda_i) = 0 & \text{otherwise} \end{aligned} \right. \end{split}$$

• Myopic iteration at each step

#### **Random Update Algorithm**

 $\begin{cases} p_i^{(n+1)} = p_{i,PUA}^{(n+1)}(p_{-i}^{(n)},\lambda_i) & \text{ with probability } \pi_i \\ p_i^{(n+1)} = p_i^{(n)} & \text{ with probability } 1 - \pi_i \end{cases}$ 



• Myopic iteration and randomized delays in update



#### **Optical Networks**

- A preferred means of transmission for signals
  - Low loss
  - Low levels of undesirable transmission impairment
  - Strong immunity to electromagnetic interference
  - Long life-span
- Network Management:
  - Centrally managed optical layer  $\rightarrow$  one controlled in distributed fashion
  - Add/drop dynamics





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#### An Example of Optical Network Topology



- 1. Channel-channel interference
- 2. Spontaneous Emission Noise (ASE)
- 3. Multi-stage amplifications
- 4. More complicated network topology



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Mobile Users



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**From Wireless to Optical Network** 



$$OSNR_{i} = \frac{u_{i}}{n_{0,i} + \sum_{j \in \mathcal{M}} \Gamma_{i,j} u_{j}} \quad \forall i \in \mathcal{M}$$







# **Game and Nash Solution**

- A game defined by  $\langle N, (A_i), (J_i) \rangle$ 
  - N=(1,2,...M), number of players
  - $(A_i)_{i \in \mathbb{N}}$ : set of strategies  $[0, u_{\max}]^{\mathbb{N}}$
  - $(J_i)_{i \in \mathbb{N}}$ : preference relations represented by payoff functions:

$$J_i(u_i, u_{-i}) = \alpha_i u_i - \beta_i \ln(1 + a_i \frac{u_i}{X_{-i}})$$

• Implicit Best response function  $BR_i(u_i, u_{:i})$ 

$$a_{i}u_{i}^{*} + X_{-i}^{*} = \frac{a_{i}\beta_{i}}{\alpha_{i}}, \text{ where } X_{-i} = \sum_{j \neq i} \Gamma_{i,j}u_{j} + n_{0,i}$$

Aggregate into a matrix:

$$\tilde{\Gamma}u^* = \tilde{b}$$





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Game and Nash Solution (Cont'd)  $\begin{bmatrix} a_1 & \Gamma_{1,2} & \cdots & \Gamma_{1,M} \\ \Gamma_{2,1} & a_2 & \cdots & \Gamma_{2,M} \\ \vdots & \vdots & \ddots & \vdots \\ \Gamma_{M,1} & \Gamma_{M,2} & \cdots & a_M \end{bmatrix} \begin{bmatrix} u_1^* \\ u_2^* \\ \vdots \\ u_M^* \end{bmatrix} = \begin{bmatrix} \frac{a_1\beta_1}{\alpha_1} - n_{0,1} \\ \frac{a_2\beta_2}{\alpha_2} - n_{0,2} \\ \vdots \\ \frac{a_M\beta_M}{\alpha_M} - n_{0,M} \end{bmatrix}$  $\tilde{\Gamma} u^* = \tilde{b}$  $Im(\lambda_i)$  $\rho = \sum_{j \neq i} \Gamma_{i,j}$ Existence and Uniqueness of Solution under a sufficient condition: Strictly Diagonal Dominance:  $\sum_{i \neq i} \Gamma_{i,i} < a_i$  $Re(\lambda_i)$  $\boldsymbol{a}_{i}$  $a_i > 0 \rightarrow \widetilde{\Gamma}$  strictly positive definite **Gershgorin Disk** 



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## Nash Equilibrium and Iterative Algorithm





$$\begin{split} u_i(n+1) &= \frac{\beta_i}{\alpha_i} - \frac{X_{-i}(n)}{a_i} \\ u_i(n+1) &= \frac{\beta_i}{\alpha_i} - \frac{1}{a_i} \bigg( \frac{1}{OSNR_i(n)} - \Gamma_{i,i} \bigg) u_i(n) \end{split}$$

Nash Equilibrium Solution (Static) Iterative Algorithm (Dynamic)

- The game is in strategic form and the decisions are just made once
- The iterative algorithm is distributed.



#### Some questions:

- What is the rate of convergence in the iterative algorithm?
- How robust is the algorithm?



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**Iterative Algorithm: Rate of Convergence** 

$$\begin{split} u_i(n+1) &= \frac{\beta_i}{\alpha_i} - \frac{1}{a_i} \bigg( \frac{1}{OSNR_i(n)} - \Gamma_{i,i} \bigg) u_i(n) \\ u_i(n+1) &= \frac{\beta_i}{\alpha_i} - \frac{X_{-i}(n)}{a_i} \end{split}$$

$$\begin{array}{ll} \text{Define} & e_i(n) = u_i(n) - u^* \\ & e_i(n+1) = -\frac{1}{a_i} \sum_{j \neq i} \Gamma_{i,j} e_j(n) \\ & || \, e_i(n+1) \, ||_{\infty} = \max_i \, | \, e_i(n+1) \, | \leq \max_i (\frac{1}{a_i} \sum_{j \neq i} \Gamma_{i,j}) \, || \end{array}$$

Contraction Mapping!

Rate of convergence

 $e_i(n) \mid \mid_{\infty}$ 



Parameter  $a_i$  determines the rate of convergence!



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#### **Iterative Algorithm: Robustness**

$$\begin{split} u_i(n+1) &= \frac{\beta_i}{\alpha_i} - \frac{1}{a_i} \bigg( \frac{1}{OSNR_i(n)} - \Gamma_{i,i} \bigg) u_i(n) \\ u_i(n+1) &= \frac{\beta_i}{\alpha_i} - \frac{X_{-i}(n)}{a_i} \end{split}$$

 $W\Delta$ 

Example (3 channels):

$$e_{1}(z) = -z^{-1} \left[ \frac{1}{a_{1}} \Gamma_{1,2} e_{2}(z) + \frac{1}{a_{1}} \Gamma_{1,3} e_{3}(z) \right]$$
$$e_{2}(z) = -z^{-1} \left[ \frac{1}{a_{1}} \Gamma_{2,1} e_{1}(z) + \frac{1}{a_{1}} \Gamma_{2,3} e_{3}(z) \right]$$
$$e_{3}(z) = -z^{-1} \left[ \frac{1}{a_{1}} \Gamma_{3,1} e_{1}(z) + \frac{1}{a_{1}} \Gamma_{3,2} e_{2}(z) \right]$$



**Robustness Criteria:** 

 $||W\Delta||{<}1/\beta \text{ if }||M||\leq\beta$ 





#### **Random Update Algorithm**

$$\begin{aligned} u_i(n+1) &= \frac{\beta_i}{\alpha_i} - \frac{1}{a_i} \left( \frac{1}{OSNR_i(n)} - \Gamma_{i,i} \right) u_i(n) & \text{with probability } \pi_i \\ u_i(n+1) &= u_i(n) & \text{with probability } 1 - \pi_i \end{aligned}$$

• Can deal with the randomized delay in updates Convergence in Expectation:

$$\mathbf{E}[e_i(n+1)] = \mathbf{E}[u_i(n+1) - u_i^*] = \pi \mathbf{E}[(-\frac{1}{a_i}\sum_{j\neq i}\Gamma_{i,j}e_j(n)] + (1 - \pi_i)\mathbf{E}[e_j(n)]$$
$$\leq [-\frac{1}{a_i}\sum_{j\neq i}\Gamma_{i,j}\pi + (1 - \pi)]\mathbf{E}(e_j(n)).$$
$$< \mathbf{1}$$

Convergence in Probability (Almost surely):

$$\begin{split} \sum_{n=1}^{\infty} P(|e_i(n)| > \epsilon) &\leq \sum_{n=1}^{\infty} \frac{\mathbf{E}(|e_i(n)|)}{\epsilon} \leq \frac{1}{\epsilon} \sum_{i=1}^{\infty} \|e(n)\|_{\infty} \\ \|e(n)\|_{\infty} &\leq \kappa \|e(n-1)\|_{\infty} \leq \ldots \leq \kappa^n \|e(0)\|_{\infty}, \longrightarrow \sum_{n=1}^{\infty} P(|e_i(n)| > \epsilon) \leq \frac{K}{\epsilon(1-\kappa)} \longrightarrow \begin{array}{c} \mathbf{Converge} \\ \mathbf{In \ Probability} \\ \mathbf{Borel-Cantelli} \\ \end{split}$$



#### **Pricing Schemes**

$$J_i(u_i, u_{-i}) = \alpha_i u_i - \beta_i \ln(1 + a_i \frac{u_i}{X_{-i}})$$

- $\alpha_i$ : directly determines the pricing of unit power
- $a_i$ : influences the rate of convergence
- $\beta_i$ : closely related to the bounds on desired OSNR  $\gamma^*$

Example: proportional pricing, i.e.,  $\alpha_i = \Gamma_{i,i} k_i$ 

$$\frac{1}{\gamma_i^*}u_i^* = (\Gamma_{i,i} - a_i)u_i^* + \frac{a_i}{\Gamma_{i,i}}\frac{1}{k_i} \quad \forall i \qquad \text{or} \qquad \Sigma \mathbf{u}^* = \mathbf{v}.$$

 $a_i$  doesn't affect the upper bound of  $\gamma_i$  if  $\rho(\tilde{\Gamma}\Sigma^{-1}) < 1$ 

$$\gamma^* < \frac{1}{\sum_j \Gamma_{\mathbf{i}, \mathbf{j}}}$$

$$\begin{split} \beta_i &> \frac{1 + \left(a_i - \Gamma_{i,i} \gamma_i^*\right)}{1 - \Gamma_{i,i} \gamma_i^*} \frac{\alpha_i}{a_i} X_{-i} \quad \forall i \\ \beta_i &< \frac{\alpha_i}{a_i} [u_{max}(a_i + \sum_{j \neq i} \Gamma_{i,j}) + n_0] \quad \forall i \end{split}$$





#### **Pricing Schemes**

- More in-depth pricing schemes
- Criteria on pricing schemes
  - Stability and convergence
  - Computationally efficient
  - Fairness and allocation efficiency
- More economical basis needs to be investigated.





#### **Extension of Current Framework**

- Unanswered question under the current framework
  - Algorithms that deal with capacity constraints
  - Deal with nonlinearity effects as optimization constraints
  - Robustness of the algorithm with the presence of the uncertainties
- From strategic form to extensive form
  - Each players are allowed to make multi-stage decisions
  - Algorithm based on multi-stage decision making, that truly describes the dynamics of players.
- Two kinds of extensive forms
  - Time-based extensive game: Nash bargaining game, auctions
  - Space-based extensive game: unique to the optical networks





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